

# **The Impact of Computational Error on the Volatility Smile**

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# Inverting Black-Scholes-Merton

- Objective of option pricing models is to derive an appropriate price.
- This process can be inverted from a known option price to implied volatility.

(Latane & Rendleman, 1976; Schmalensee & Trippi, 1978)

$$c_t^m = S_t N(d_1(S_t, \tau, K, r, \hat{\sigma}_t)) - K e^{-r\tau} N(d_2(S_t, \tau, K, r, \hat{\sigma}_t))$$

$$d_1(S_t, \tau, K, r, \hat{\sigma}_t) = \frac{\ln \frac{S_t}{K} + \left( r + \frac{\hat{\sigma}_t^2}{2} \right) \tau}{\hat{\sigma}_t \sqrt{\tau}}$$

$$d_2 = d_1 - \hat{\sigma}_t \sqrt{\tau}$$

# Puzzle of the Volatility Smile

- Options that differ only by strike should have the same implied volatility.
- “To even talk about volatility smiles is schizophrenic.” (Mayhew, 1995)
- Research and trading experience uncovers smiles, smirks, and skews – all indications that the model implies multiple volatilities for the same underlying asset.

# Source of the Smile

- Previous explanations:
  - Jump return process
  - Stochastic volatility
  - Market frictions
  - Non-normality of returns
  - “Insurance” against market crashes
- **New contribution:**
  - **Computational considerations**

# Related Literature and Hypothesis

- Measurement errors in inputs can have significant impact on implied volatility.  
(Hentschel, 2003)
- Small errors in inputs can lead to large divergence in implied volatility estimate.
- This nonlinearity is an example of sensitive dependence on initial conditions.
- **Therefore, we posit that computational factors contribute significantly to the volatility smile.**

# Literature Problems

- Few papers discuss computational matters explicitly.
- Root finding technique and tolerance are rarely mentioned.
- Overwhelming majority of papers on this topic make no mention of how implied volatility is calculated.

# Closed-form Approximations

- Several formulas for implied volatility exist.
  - Often require relaxing assumptions or good only in specific cases.
  - Useful in spreadsheet and pedagogical applications.
  - Provide a starting point for iterative techniques.

# Iterative Root Finding Techniques

- Five common techniques:
  - Bisection
  - Secant
  - Regula Falsi (False Position)
  - Dekker-Brent (Commonly used by Matlab)
  - Newton-Raphson (Most commonly referenced method)



# Theory

- The reflection points can be considered ideal starting points for the Newton-Raphson method. (Manaster & Kohler, 1982)

$$\sigma = \sqrt{\frac{2}{\tau} \cdot \left| \ln \left( \frac{S}{K} \right) + r\tau \right|}$$

- Theorem 1 discusses conditions for quadratic convergence in addition to over- and under-estimation.

# Numerical Precision

- Computer models are discrete approximations of theoretically continuous processes.
- Gaussian density cannot be integrated, so further approximations are necessary.
- Results presented here use R (package Rmpfr) for quadruple precision arithmetic (128-bit storage).

# Process

- Methodology:
  - Generate Black-Scholes-Merton prices, varying exercise price over a wide range of moneyness.
  - Use these “perfect” prices to estimate implied volatility.
  - Generate graph of implied volatility.

# Parameters

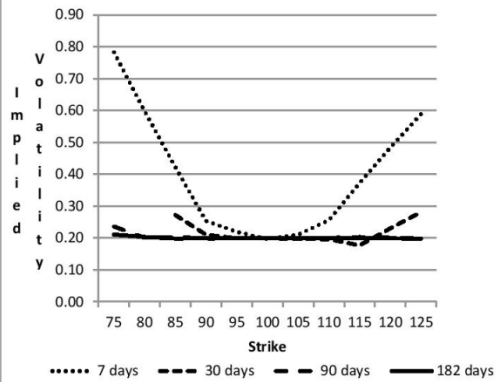
- These are the same across all simulations:
  - Spot = \$100
  - Strike ranges from \$75 to \$125 in \$5 increments
  - Interest rate = 4%
  - Expiration = 7, 30, 90, and 182 days
  - Volatility = 20%

# Factors

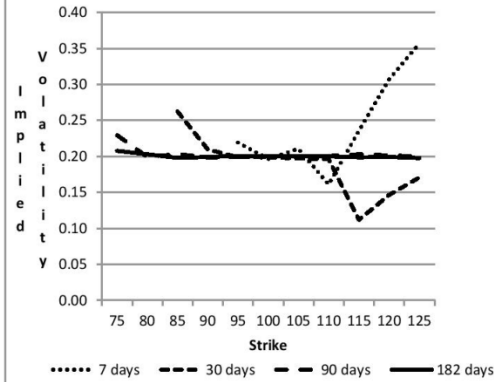
- Several factors influence the shape of the volatility smile:
  - Numerical precision (tolerance of 0.01, 0.00001, and machine epsilon  $2^{-52}$ )
  - Quotation unit (“continuous”, penny, sixteenths)
  - Five root finding techniques
  - Initial input/interval

# Results

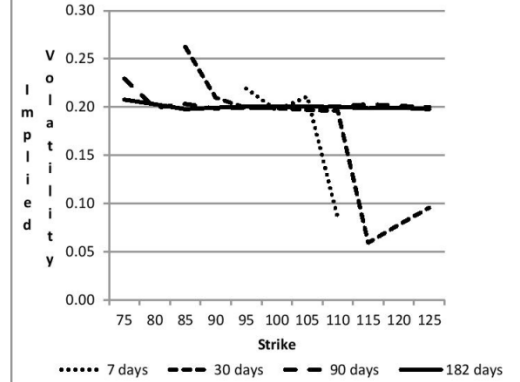
16ths prices, tolerance = 0.01



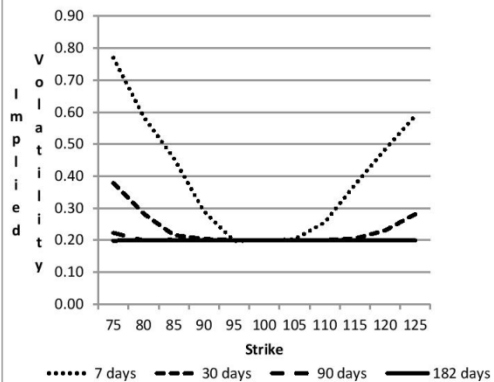
16ths prices, tolerance = 0.00001



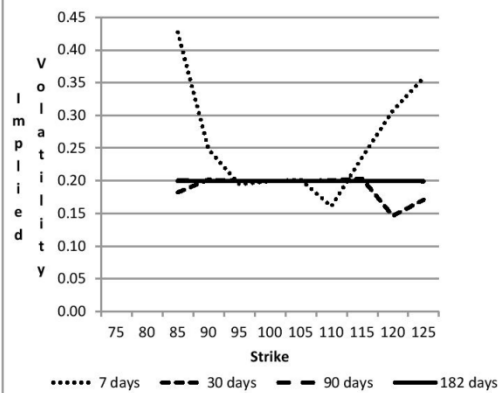
16ths prices, tolerance = ME



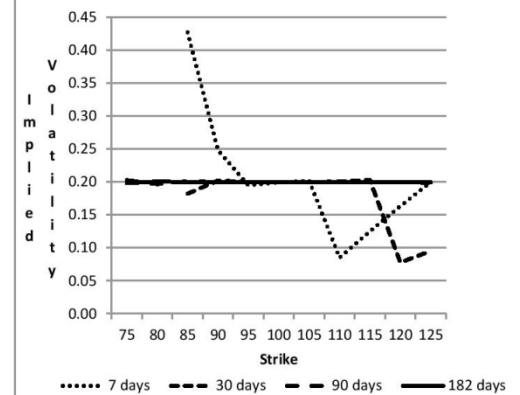
penny prices, tolerance = 0.01



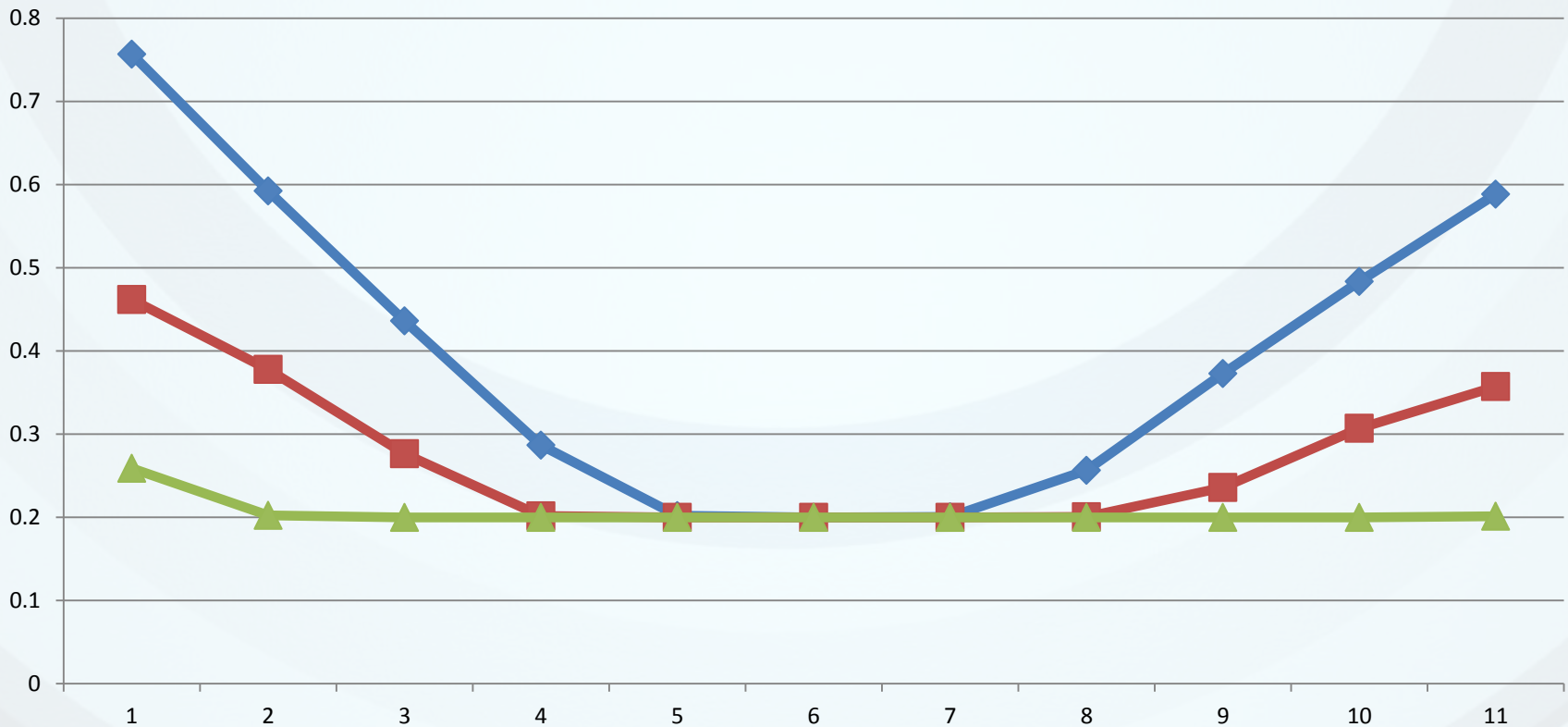
penny prices, tolerance = 0.00001



penny prices, tolerance = ME



# Results: Numerical Precision



- The smile dissipates as tolerance shrinks from penny (blue) to machine epsilon (green)

# Results

- Despite full knowledge of the volatility used to generate Black-Scholes-Merton prices, the inversion process creates a wide variety of smiles, skews, and smirks.
- Root finding technique, initial input, quotation rounding, and numerical precision all contribute to the shape of the volatility smile.



# Measuring Smiles: Empirical Result

- Assume that the closest to ATM option reveals the true volatility.
- Use that volatility to price other options and calculate sum-of-squared deviations as a measure of the smile.
- Allows comparison of methods.
- Illustrative example of Ebay: 40% of the smile is due to computational factors.

# Implications

- We cannot remain cavalier in calculating implied volatility.
- There are apparently no choices that solve the computational problems.
- Other factors likely contribute to smile effects, but possibly cannot be disentangled from computational errors.

We welcome your questions  
and comments.

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